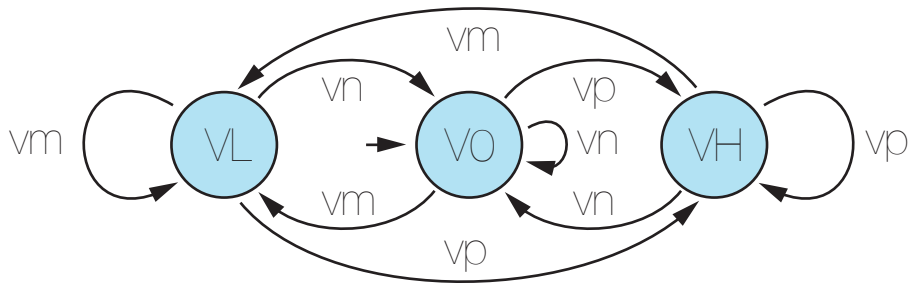
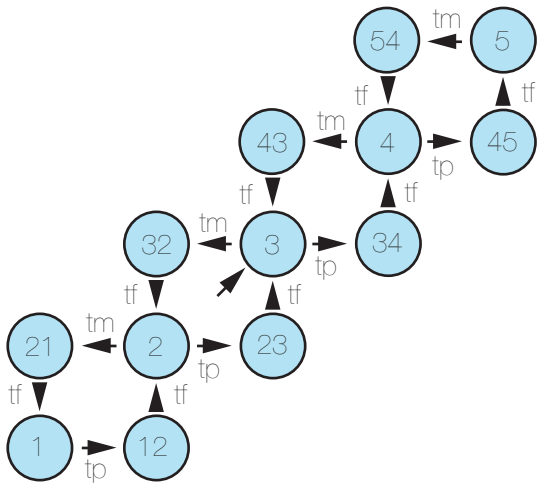


T_sensor



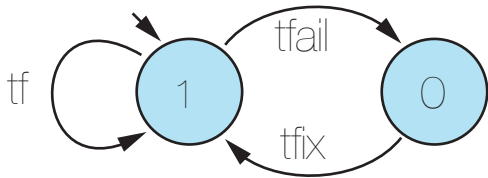
$$E_o = \{vn, vm, vp\}, E_c = \{\}$$

T_switch



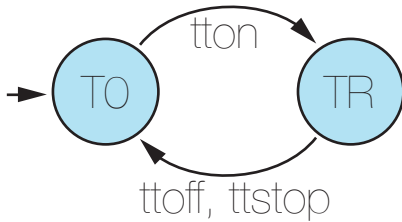
$$E_o = \{tf\}, E_c = \{tp, tm\}$$

T_fail



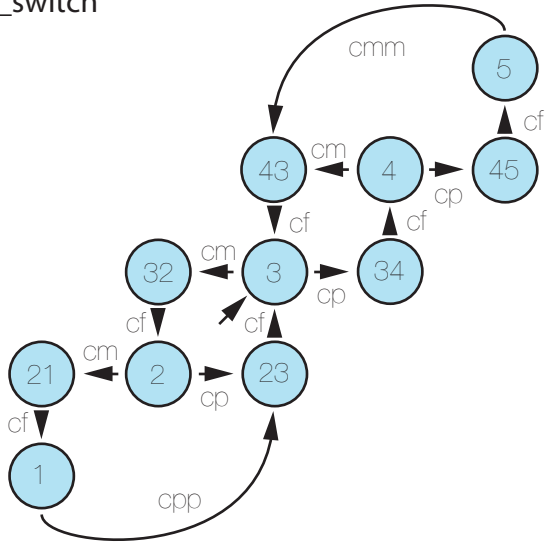
$$E_o = \{tf\}, E_c = \{\}$$

T_timer



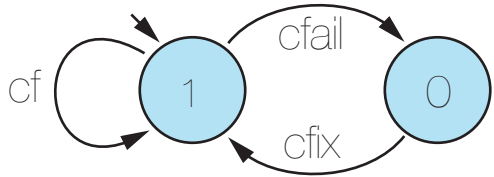
$E_o = \{ttstop\}$, $E_c = \{tton, ttoff\}$

C_switch



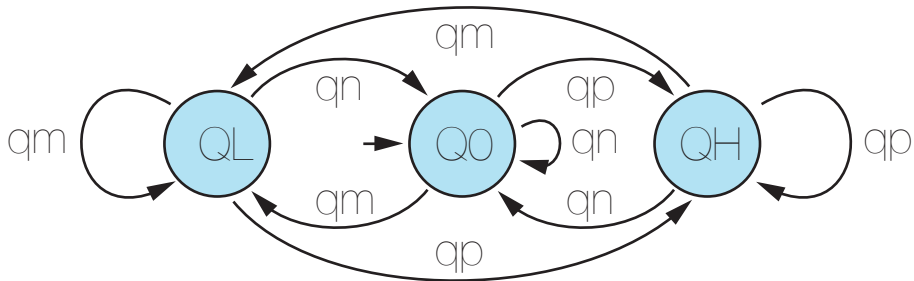
$$E_o = \{cf\}, E_c = \{cp, cpp, cm, cmm\}$$

F_fail



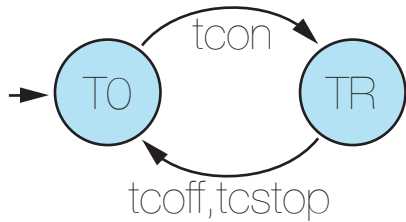
$$E_o = \{cf\}, E_c = \{\}$$

C_sensor



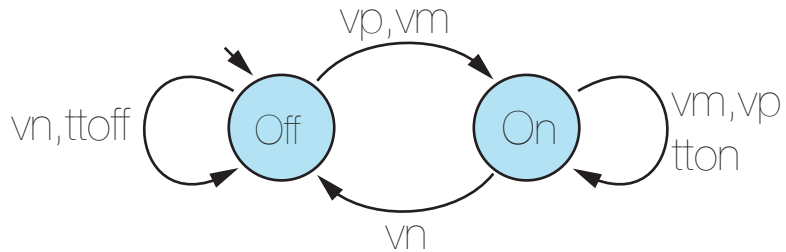
$$E_o = \{qn, qm, qp\}, E_c = \{\}$$

C_timer

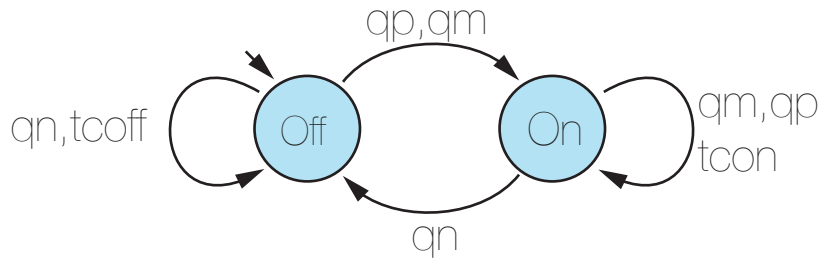


$E_o = \{tcstop\}$, $E_c = \{tcon, tcoff\}$

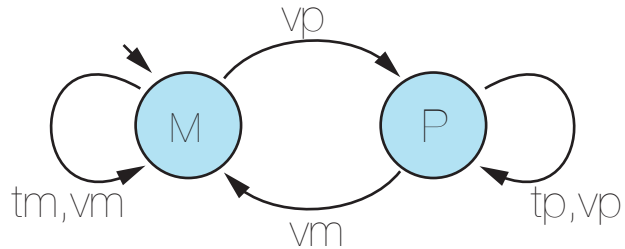
T_con1



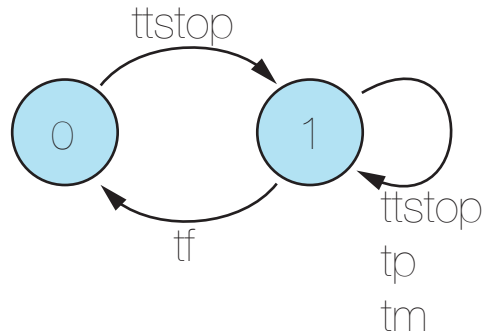
C_con1



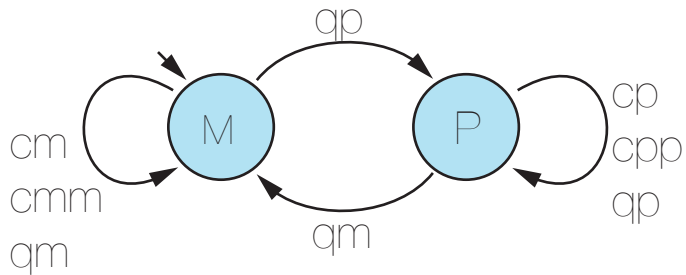
T_con2



T_con3



C_con2



C_con3

